

IN THE CLAIMS:

This listing of claims will replace all prior versions and listings of the claims:

1. (Original) A tool guiding apparatus for guiding a tool along a path on a surface to be processed, said apparatus comprising:
at least one path-defining means adapted to be attached to the surface,
automatic tool actuation means adapted to advance the tool along the path,
wherein the automatic tool actuation means comprises a flexible force-transferring element comprising a first end and a second end, the first end being attached to the automatic tool actuation means and the second end being attached to the tool.
2. (Original) A tool guiding apparatus according to claim 1, wherein the path-defining means is adapted to engage at least a part of the flexible force-transferring element.
3. (Currently Amended) A tool guiding apparatus according to claim 1 ~~any of the preceding claims~~, wherein the path-defining means comprises a wheel adapted to engage at least a part of the force-transferring element.
4. (Currently Amended) A tool guiding apparatus according to claim 1 ~~any of the preceding claims~~, wherein the automatic tool actuation means is adapted to be attached to the surface.
5. (Original) A tool guiding apparatus according to claim 4, wherein at least one of the automatic tool actuation means and the at least one path-defining means comprises at least one vacuum cup.
6. (Currently Amended) A tool guiding apparatus according to claim 1 ~~any of claims 1-5~~, wherein the tool is a knife with a cutting edge.
7. (Original) A tool guiding apparatus according to claim 6, wherein at least a part of the cutting edge extends in a direction transverse to a line defined by at least a part of the force-transferring element.
8. (Currently Amended) A tool guiding apparatus according to claim 5 ~~any of claims 5-7~~, wherein the vacuum cup and the wheel are interconnected by a moment arm.
9. (Currently Amended) A tool guiding apparatus according to claim 3 ~~any of claims 3-8~~, wherein the radius of the wheel is substantially equal to the radius of a windscreen of an automobile.
10. (Currently Amended) A tool guiding apparatus according to claim 3 ~~any of claims 3-9~~,

wherein the wheel is releasably attached to the path defining means.

11. (Currently Amended) A tool guiding apparatus according to claim 3 ~~any of claims 3-10~~, further comprising a plurality of interchangeable wheels at least two of said wheels having different radii.

12. (Currently Amended) A tool guiding apparatus according to claim 5 ~~any of claims 5-11~~, wherein at least a part of the surface of the wheel comprises a friction increasing material.

13. (Currently Amended) A tool guiding apparatus according to claim 5 ~~any of claims 5-12~~, wherein at least a part of the force transferring element comprises a friction increasing material.

14. (Currently Amended) A tool guiding apparatus according to claim 1 ~~any of the preceding claims~~, wherein the automatic tool actuation means comprises a motor.

15. (Original) A tool guiding apparatus according to claim 14, wherein the motor is electrical.

16. (Currently Amended) A tool guiding apparatus according to claim 1 ~~any of the preceding claims~~, wherein the automatic tool actuation means are adapted to pull the tool along the path.

17. (Currently Amended) A tool guiding apparatus according to claim 6 ~~any of claims 6-16~~, wherein the knife is releasably attached to a fixture.

18. (Currently Amended) A tool guiding apparatus according to claim 6 ~~any of claims 6-17~~, wherein the fixture comprises a means for activating the motor.

19. (Original) A tool guiding apparatus according to claim 18, wherein the means for activating the motor is adapted to control the speed of the motor.

20. (Currently Amended) A tool guiding apparatus according to claim 18 ~~claims 18 or 19~~, wherein the means for activating the motor is wireless.

21. (Currently Amended) A tool guiding apparatus according to claim 14 ~~any of claims 14-20~~, further comprising control means for controlling the speed of the motor.

22. (Original) A method for guiding a tool along a path on a surface to be processed, said method comprising the steps of:

attaching at least one path defining means to the surface to be processed, and
advancing the tool along the path by activating an automatic tool actuation means.

23. (Original) A method according to claim 22, further comprising the step of attaching the automatic tool actuation means to the surface.